

# Savitribai Phule Pune University

## Faculty of Science & Technology



Curriculum/Syllabus  
for  
**Second Year**  
**Bachelor of Engineering**  
**(Choice Based Credit System)**  
**Automation & Robotics Engineering**  
**(2019 Course)**

**Board of Studies - Automobile and Mechanical Engineering**  
(With Effect from Academic Year 2021-22)

**Savitribai Phule Pune University**  
**Board of Studies - Automobile and Mechanical Engineering**  
**Undergraduate Program – Automation & Robotics Engineering (2019 pattern)**

Course Code	Course Name	Teaching Scheme (Hours/Week)			Examination Scheme and Marks						Credit			
		TH	PR	TUT	ISE	ESE	TW	PR	OR	TOTAL	TH	PR	TUT	TOTAL
<b>Semester-III</b>														
<a href="#">202041</a>	Solid Mechanics	4	2	-	30	70	-	50	-	150	4	1	-	5
<a href="#">202042</a>	Solid Modeling and Drafting	3	2	-	30	70	-	50	-	150	3	1	-	4
<a href="#">202044</a>	Engineering Materials and Metallurgy	3	2	-	30	70	25	-	-	125	3	1	-	4
<a href="#">202521</a>	Electrical Technology	3	2	-	30	70	-	-	25	125	3	1	-	4
<a href="#">202522</a>	Industrial Electronics	3	2	-	30	70	25	-	-	125	3	1	-	4
<a href="#">202045</a>	Geometric Dimensioning and Tolerancing Lab	-	2	-	-	-	25	-	-	25	-	1	-	1
<a href="#">202046</a>	Audit Course - III	-	-	-	-	-	-	-	-	-	-	-	-	-
	<b>Total</b>	<b>16</b>	<b>12</b>	<b>-</b>	<b>150</b>	<b>350</b>	<b>75</b>	<b>100</b>	<b>25</b>	<b>700</b>	<b>16</b>	<b>6</b>	<b>-</b>	<b>22</b>
<b>Semester-IV</b>														
<a href="#">207002</a>	Engineering Mathematics - III	3	-	1	30	70	25	-	-	125	3	-	1	4
<a href="#">202047</a>	Kinematics of Machinery	3	2	-	30	70	-	-	25	125	3	1	-	4
<a href="#">202523</a>	Fluid & Thermal Engineering	3	2	-	30	70	-	25	-	125	3	1	-	4
<a href="#">202524</a>	Principles of Robotics	3	2	-	30	70	-	25	-	125	3	1	-	4
<a href="#">202050</a>	Manufacturing Processes	3	-	-	30	70	-	-	-	100	3	-	-	3
<a href="#">202051</a>	Machine Shop	-	2	-	-	-	50	-	-	50	-	1	-	1
<a href="#">202052</a>	Project Based Learning - II	-	4	-	-	-	50	-	-	50	-	2	-	2
<a href="#">202053</a>	Audit Course - IV	-	-	-	-	-	-	-	-	-	-	-	-	-
	<b>Total</b>	<b>15</b>	<b>12</b>	<b>1</b>	<b>150</b>	<b>350</b>	<b>125</b>	<b>50</b>	<b>25</b>	<b>700</b>	<b>15</b>	<b>6</b>	<b>1</b>	<b>22</b>
<p><b>Abbreviations:</b> TH: Theory, PR: Practical, TUT: Tutorial, ISE: In-Semester Exam, ESE: End-Semester Exam, TW: Term Work, OR: Oral</p>														
<p><b>Note:</b> Interested students of SE (Automation &amp; Robotics Engineering) can opt for any one of the audit course from the list of audit courses prescribed by BoS (Mechanical and Automobile Engineering)</p>														
<p><b>Instructions</b></p> <ul style="list-style-type: none"> <li>• Practical/Tutorial must be conducted in three batches per division only.</li> <li>• Minimum number of required Experiments/Assignments in PR/ Tutorial shall be carried out as mentioned in the syllabi of respective subjects.</li> <li>• Assessment of tutorial work has to be carried out as a term-work examination. Term-work Examination at second year of engineering course shall be internal continuous assessment only.</li> <li>• Project based learning (PBL) requires continuous mentoring by faculty throughout the semester for successful completion of the tasks selected by the students per batch. While assigning the teaching workload of 2 Hrs/week/batch needs to be considered for the faculty involved. The Batch needs to be divided into sub-groups of 5 to 6 students. Assignments / activities / models/ projects etc. under project based learning is carried throughout semester and Credit for PBL has to be awarded on the basis of internal continuous assessment and evaluation at the end of semester.</li> <li>• Audit course is mandatory but non-credit course. Examination has to be conducted at the end of Semesters for award of grade at institute level. Grade awarded for audit course shall not be calculated for grade point &amp; CGPA.</li> </ul>														

**202041 - Solid Mechanics**

Teaching Scheme	Credits	Examination Scheme
Theory : 04 Hr./Week Practical : 02 Hr./Week	05 Theory : 04 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Practical : 50 Marks

**Prerequisite Courses**

Engineering Mathematics- I and II, Systems in Mechanical Engineering, Engineering Mechanics

**Course Objectives**

1. To acquire basic knowledge of stress, strain due to various types of loading.
2. To draw Shear Force and Bending Moment Diagram for transverse loading.
3. To determine Bending, Shear stress, Slope and Deflection on Beam.
4. To solve problems of Torsional shear stress for shaft and Buckling for the column.
5. To apply the concept of Principal Stresses and Theories of Failure.
6. To utilize the concepts of Solid Mechanics on application based combined mode of loading.

**Course Outcomes**

On completion of the course, learner will be able to

- CO1. DEFINE various types of stresses and strain developed on determinate and indeterminate members.
- CO2. DRAW Shear force and bending moment diagram for various types of transverse loading and support.
- CO3. COMPUTE the slope & deflection, bending stresses and shear stresses on a beam.
- CO4. CALCULATE torsional shear stress in shaft and buckling on the column.
- CO5. APPLY the concept of principal stresses and theories of failure to determine stresses on a 2-D element.
- CO6. UTILIZE the concepts of SFD & BMD, torsion and principal stresses to solve combined loading application based problems.

**Course Contents**

**Unit I** **Simple stresses & strains** **[10 Hr.]**

**Simple Stress & Strain:** Introduction to types of loads (Static, Dynamic & Impact Loading) and various types of stresses with applications, Hooke's law, Poisson's ratio, Modulus of Elasticity, Modulus of Rigidity, Bulk Modulus. Interrelation between elastic constants, Stress-strain diagram for ductile and brittle materials, factor of safety, Stresses and strains in determinate and indeterminate beam, homogeneous and composite bars under concentrated loads and self-weight, Thermal stresses in plain and composite members

**Unit II** **Shear Force & Bending Moment Diagrams** **[08 Hr.]**

**SFD & BMD:** Introduction to SFD, BMD with application, SFD & BMD for statically determinate beam due to concentrated load, uniformly distributed load, uniformly varying load, couple and combined loading, Relationship between rate of loading, shear force and bending moment, Concept of zero shear force, Maximum bending moment, point of contra-flexure

**Unit III** **Stresses, Slope & Deflection on Beams** **[12 Hr.]**

**Bending Stress on a Beam:** Introduction to bending stress on a beam with application, Theory of Simple bending, assumptions in pure bending, derivation of flexural formula, Moment of inertia of common cross section (Circular, Hollow circular, Rectangular, I & T), Bending stress distribution along the same cross-section

**Shear Stress on a Beam:** Introduction to transverse shear stress on a beam with application, shear stress distribution diagram along the Circular, Hollow circular, Rectangular, I & T cross-section

**Slope & Deflection on a Beam:** Introduction to slope & deflection on a beam with application, slope, deflection and Radius of Curvature, Macaulay's Method, Slope and Deflection for all standard beams

<b>Unit IV</b>	<b>Torsion, Buckling</b>	<b>[08 Hr.]</b>
<p><b>Torsion of circular shafts:</b> Introduction to torsion on a shaft with application, Basic torsion formulae and assumption in torsion theory, Torsion in stepped and composite shafts, Torque transmission on strength and rigidity basis, Torsional Resilience</p> <p><b>Torsion on Thin-Walled Tubes:</b> Introduction of Torsion on Thin-Walled Tubes Shaft and its application</p> <p><b>Buckling of columns:</b> Introduction to buckling of column with its application, Different column conditions and critical, safe load determination by Euler's theory. Limitations of Euler's Theory</p>		
<b>Unit V</b>	<b>Principal Stresses, Theories of Failure</b>	<b>[08 Hr.]</b>
<p><b>Principal Stresses:</b> Introduction to principal stresses with application, Transformation of Plane Stress, Principal Stresses and planes (Analytical method and Mohr's Circle), Stresses due to combined Normal and Shear stresses</p> <p><b>Theories of Elastic failure:</b> Introduction to theories of failure with application, Maximum principal stress theory, Maximum shear stress theory, Maximum distortion energy theory, Maximum principal strain theory, Maximum strain energy theory</p>		
<b>Unit VI</b>	<b>Application based combined loading &amp; stresses</b> (Based on load and stress condition studied in Unit I to Unit V)	<b>[08 Hr.]</b>
<p>Introduction to the Combined Loading and various stresses with application, Free Body Diagram and condition of Equilibrium for determining internal reaction forces, couples for 2-D system, Combined stresses at any cross-section or at any particular point for Industrial and Real life example for the following cases: Combined problem of Normal type of Stresses (Tensile, Compressive and Bending stress), Combined problem of Shear type of stresses (Direct and Torsional Shear stresses), Combined problem of Normal and Shear type of Stresses</p>		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
<ol style="list-style-type: none"> <li>1. R. K. Bansal, "Strength of Materials", Laxmi Publication</li> <li>2. S. Ramamurtham, "Strength of material", Dhanpat Rai Publication</li> <li>3. S.S. Rattan, "Strength of Material", Tata McGraw Hill Publication Co. Ltd.</li> <li>4. B.K. Sarkar, "Strength of Material", McGraw Hill New Delhi</li> <li>5. Singer and Pytel, "Strength of materials", Harper and row Publication</li> <li>6. R. C. Hibbeler, "Mechanics of Materials", Prentice Hall Publication</li> </ol>		
<b>Reference Books</b>		
<ol style="list-style-type: none"> <li>1. Egor. P. Popov, "Introduction to Mechanics of Solids", Prentice Hall Publication</li> <li>2. G. H. Ryder, "Strength of Materials", Macmillan Publication</li> <li>3. Beer and Johnston, "Strength of materials", CBS Publication</li> <li>4. James M. Gere, "Mechanics of Materials", CL Engineering</li> <li>5. Timoshenko and Young, "Strength of Materials", CBS Publication, Singapore</li> <li>6. Prof. S.K. Bhattacharyya, IIT Kharagpur, "NPTEL Web course material" <a href="https://drive.google.com/file/d/1N2EYv9ofPimIT2OSMZeMrSxe68Ulclei/view?usp=sharing">https://drive.google.com/file/d/1N2EYv9ofPimIT2OSMZeMrSxe68Ulclei/view?usp=sharing</a></li> </ol>		
<b>Guidelines for Laboratory Conduction</b>		
The student shall complete the following activity as a Term Work		
<p><i>The Termwork shall consist of completion of Practicals, Self-learning Study Assignments and Presentations. Practical examination shall be based on the Termwork undertaken during the semester.</i></p> <p><b>Practical</b> (Any 6 experiments out of experiment no 1 to 8 from the following list whereas experiment no. 9 and 10 are mandatory. Minimum One experiment must be performed on IoT platform- Virtual Lab):</p> <ol style="list-style-type: none"> <li>1. Tension test for Ductile material using extensometer on Universal Testing Machine.</li> <li>2. Compression test for Brittle material on Universal Testing Machine.</li> <li>3. Shear test of ductile material on Universal Testing Machine.</li> </ol>		

4. Tension test of Plastic/Composite material on low load capacity Tensile Testing Machine.
5. Measurement of stresses and strains using strain gauges.
6. Experimental verification of flexural formula in bending for cantilever, Simple supported beam.
7. Study and interpretations of stress distribution pattern using Polariscope for Plastic/Acrylic.
8. Experimental verification of torsion formula for circular bar.
9. Verification of results of any two from experiments no 1-8 using any FEA software tools.
10. **Self-learning study practical:** *Following topics are distributed among the group of 3-5 Students and groups need to present and also submit the slides/poster on TW file.*
  - a. Experimental stress analysis, Strain Gauges rosette with case study.
  - b. Residual stresses and Fatigue life with case study.
  - c. Effect of heat treatment on the mechanical properties of a metal with case study.
  - d. Mechanical properties of materials, Stresses and Design of components with case study.
  - e. Failure Mode Analysis and Stresses with case study.

## 202042 - Solid Modeling and Drafting

Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	04 Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Practical : 50 Marks

### Prerequisite Courses

Systems in Mechanical Engineering, Engineering Graphics, Engineering Mathematics - I and II

### Course Objectives

1. To understand basic structure of CAD systems and their use to create geometric models of simple engineering parts
2. To introduce the curves and surfaces and their implement in geometric modeling
3. To apply basic concepts of 3D modeling, viewing and evaluate mass properties of components and assemblies
4. To apply geometrical transformations in CAD models
5. To understand data exchange standards and translators for various applications
6. To create engineering drawings, design documentation and use in manufacturing activities

### Course Outcomes

On completion of the course, learner will be able to

- CO1. UNDERSTAND basic concepts of CAD system, need and scope in Product Lifecycle Management
- CO2. UTILIZE knowledge of curves and surfacing features and methods to create complex solid geometry
- CO3. CONSTRUCT solid models, assemblies using various modeling techniques & PERFORM mass property analysis, including creating and using a coordinate system
- CO4. APPLY geometric transformations to simple 2D geometries
- CO5. USE CAD model data for various CAD based engineering applications viz. production drawings, 3D printing, FEA, CFD, MBD, CAE, CAM, etc.
- CO6. USE PMI & MBD approach for communication

### Course Contents

#### Unit I Fundamentals of 3D Modeling [08 Hr.]

Introduction, Product Life Cycle, CAD tools in the design process of Product Cycle, Scope of CAD, Software Modules - Operating System (OS) module, Geometric module, application module, programming module, communication module, Computer Aided Design - Features, requirements and applications

3D Modeling approach - Primitive, Features and Sketching, Types of Geometric models - 2½ extrusions, axisymmetric, composite, 3D objects, difference between wireframe, surface & solid modeling, Modeling strategies

**Model viewing:** VRML web-based viewing

#### Unit II Curves & Surfaces [08 Hr.]

**Curves:** Methods of defining Point, Line and Circle, Curve representation - Cartesian and Parametric space, Analytical and Synthetic curves, Parametric equation of line, circle, ellipse, Continuity ( $C^0$ ,  $C^1$  &  $C^2$ ), Synthetic Curves - Hermit Cubic Spline, Bezier, B-Spline Curve, Non-Uniform Rational B-Spline curves (NURBS)

**Surfaces:** Surface representation, Types of Surfaces, Bezier, B-Spline, NURBS Surface, Coons patch surface, Surface Modeling

**Reverse Engineering:** Introduction, Point Cloud Data (PCD), PCD file formats, Quality issues in PCD, Requirements for conversion of surface models into solid models, Applications of PCD

<b>Unit III</b>	<b>Solid Modeling</b>	<b>[08 Hr.]</b>
<p>Introduction, Geometry and Topology, Solid entities, Solid representation, Fundamentals of Solid modeling, Half spaces, Boundary representation (B-Rep), Constructive Solid Geometry (CSG), Sweep representation, Analytical solid modeling, Parametric solid modeling, feature based modeling, etc., Euler Equation (Validity of 3D solids), Mass Property Calculations</p> <p>Introduction to Assembly Modeling, Assemblies (Top-down and Bottom-up approach), Design for Manufacturing [DFM], Design for Easy Assembly &amp; Disassembly [DFA], Design for Safety</p>		
<b>Unit IV</b>	<b>Geometric Transformation</b>	<b>[08 Hr.]</b>
<p>Introduction, Geometric Transformations, Translation, Scaling, Rotation, Reflection/Mirror, Shear, Homogeneous Transformation, Inverse Transformation, Concatenated Transformation (limited to 2D objects with maximum 3 points only), Coordinate systems - Model (MCS), Working (WCS), Screen (SCS) coordinate system, Mapping of coordinate systems</p> <p>Projections of geometric models - Orthographic and Perspective projections, Design and Engineering applications</p>		
<b>Unit V</b>	<b>CAD Data Exchange</b>	<b>[08 Hr.]</b>
<p>Introduction, CAD Kernels, CAD Data File, Data interoperability, CAD Data Conversions, challenges in CAD data conversions/remedies, Direct Data Translators, Neutral 3D CAD file formats (DXF, IGES, PDES, STEP, ACIS, Parasolid, STL, etc.), Data Quality</p> <p>Requirements of CAD file format for 3D Printing (Additive Manufacturing), CAE, FEA, CFD, CAM (Subtractive Manufacturing), Multi-Body Dynamics (Motion Simulations), Computer Aided Inspection (CAI), Computer Aided Technologies (CAx), AR/VR applications, etc., Introduction to CAD Geometry Clean-up for different applications</p>		
<b>Unit VI</b>	<b>CAD Customization &amp; Automation</b>	<b>[08 Hr.]</b>
<p>Introduction, Limitations of 2D drawings, Introduction to Product and Manufacturing Information (PMI), Model Based Definitions (MBD), Applications of PMI &amp; MBD</p> <p><b>CAD Customization:</b> Introduction, advantages and disadvantages, Applications of Customization Interfaces, Product Customization Approaches - Part Modeling Customization, Assembly Modeling Customization, Drawing sheets &amp; PMI Customization, CAD Automation</p> <p>Introduction to Application Programming Interface (API), Structures of APIs, Coding/Scripting for customization, Introduction to CAD API Development, CAD Files &amp; application handling</p>		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
<ol style="list-style-type: none"> <li>1. Zeid, I and Sivasubramania, R., (2009), "CAD/CAM : Theory and Practice", 2nd edition, McGraw Hill Education, ISBN-13: 978-0070151345</li> <li>2. Rao, P. N., (2017), "CAD/CAM: Principles and Applications", 3rd edition, McGraw Hill Education, ISBN-13: 978-0070681934</li> <li>3. Chang, Kuang-Hua, (2015), "e-Design: Computer-Aided Engineering Design", Academic Press, ISBN-13: 978-0123820389</li> </ol>		
<b>Reference Books</b>		
<ol style="list-style-type: none"> <li>1. Lee, Kunwoo, (1999), "Principles of CAD/CAM/CAE Systems", Pearson/Addison-Wesley, ISBN-13: 978-0201380361</li> <li>2. Bordegoni, Monica and Rizzi, Caterina, (2011), "Innovation in Product Design: From CAD to Virtual Prototyping", Springer, ISBN-13: 978-1447161875</li> <li>3. Vukašinovic, Nikola and Duhovnik, Jože, (2019), "Advanced CAD Modeling: Explicit, Parametric, Free-Form CAD and Re-engineering", Springer, ISBN-13: 978-3030023980</li> <li>4. Um, Dugan, (2018), "Solid Modeling and Applications: Rapid Prototyping, CAD and CAE Theory", 2<sup>nd</sup> edition, Springer, ISBN-13: 978-3319745930</li> <li>5. Rogers, D. and Adams, J. A., (2017), "Mathematical Elements for Computer Graphics", 2<sup>nd</sup> edition, McGraw Hill Education, ISBN-13: 978-0070486775</li> </ol>		

6. Hearn, D. D. and Baker, M. P., (2013), "Computer Graphics with OpenGL", 4<sup>th</sup> edition, Pearson Education India, ISBN-13: 978-9332518711
7. Gokhale, N. S., Deshpande, S. S., Bedekar, S. V. and Thite, A. N., (2008), "Practical Finite Element Analysis", Finite to Infinite, Pune, India, ISBN-13: 978-8190619509
8. Lee Ambrosius, (2015), "AutoCAD<sup>®</sup> Platform Customization: User Interface, AutoLISP<sup>®</sup>, VBA, and Beyond", John Wiley & Sons, Inc., IN, ISBN-13: 978-1118798904
9. Bucalo, Joe and Bucalo, Neil, (2007), "Customizing SolidWorks for Greater Productivity", Sheet Metal Guy, LLC, ISBN-13: 978-0979566608
10. Ziethen, Dieter R. (2012), "CATIA V5: Macro Programming with Visual Basic Script", McGraw-Hill Companies, Inc./Carl Hanser Verlag München, ISBN-13: 978-0071800020, ISBN: 978-007180003-7
11. Programming Manuals of Softwares

### **Guidelines for Laboratory Conduction**

The student shall complete the following activity as a Term Work Journal

#### **Practical**

*The student shall complete the following Practical in laboratory using suitable CAD modeling software. Learner will demonstrate skills to communicate drawings as per industry standards.*

1. 2-D sketching with geometrical and dimensional constraints
2. Solid & Surface modeling for simple mechanical components (Output file as Production drawing and Model Based Definition (MBD))
  - (a) Sheet-Metal
  - (b) Machining
  - (c) Fabrication
  - (d) Casting
  - (e) Forgings
  - (f) Plastic Molding
3. Assembly modeling (Output file as Assembly drawing and detailing) of the parts modeled in Practical assignment-2 using proper assembly constraint conditions and generation of exploded view for assemblies like Couplings, Clutches, Gear Assemblies, Engine/Pump/Turbine Components, Valves, Machine Tools, Automobile Components, Gear-Box, Pressure Vessels, etc.
4. Reverse Engineering of surface/solid modeling using Point Cloud Data.
5. Assembly Modeling by importing parts/components from free online resources like CAD and Product development software websites, forums, blogs, etc.
6. Demonstration on CAD Customization (with introduction to programming languages, interfacing)



202044 - Engineering Materials and Metallurgy		
Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	<b>04</b> Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Term Work : 25 Marks
<b>Prerequisite Courses</b> Higher Secondary Science courses, Engineering Physics, Engineering Chemistry, Systems in Mechanical Engineering		
<b>Course Objectives</b> 1. To impart fundamental knowledge of material science and engineering. 2. To establish significance of structure property relationship. 3. To explain various characterization techniques. 4. To indicate the importance of heat treatment on structure and properties of materials. 5. To explain the material selection process.		
<b>Course Outcomes</b> On completion of the course, learner will be able to CO1. COMPARE crystal structures and ASSESS different lattice parameters. CO2. CORRELATE crystal structures and imperfections in crystals with mechanical behavior of materials. CO3. DIFFERENTIATE and DETERMINE mechanical properties using destructive and non-destructive testing of materials. CO4. IDENTIFY & ESTIMATE different parameters of the system viz., phases, variables, component, grains, grain boundary, and degree of freedom. etc. CO5. ANALYSE effect of alloying element & heat treatment on properties of ferrous & nonferrous alloy. CO6. SELECT appropriate materials for various applications.		
<b>Course Contents</b>		
<b>Unit I</b>	<b>Crystal Structures and Deformation of Materials</b>	<b>[08 Hr.]</b>
<b>Crystal Structures:</b> Study of Crystal structures BCC, FCC, HCP and lattice parameters & properties, Miller indices, Crystal imperfections, and Diffusion Mechanisms <b>Material Properties:</b> Mechanical (Impact, hardness, etc.), Electrical, optical and Magnetic properties <b>Deformation of Materials:</b> Elastic deformation, Plastic deformation: slip, twinning, work hardening, baushinger effect, recovery, re-crystallization and grain growth, Fracture: Types of fractures (brittle, ductile), Creep & Fatigue failures		
<b>Unit II</b>	<b>Material Testing and Characterization Techniques</b>	<b>[06 Hr.]</b>
<b>Destructive Testing:</b> Impact test, Cupping test and Hardness test <b>Non-Destructive Testing:</b> Eddy current test, Sonic & Ultrasonic testing, X-ray Radiography testing (Principle and Applications only) <b>Microscopic Techniques:</b> Sample Preparation and etching procedure, optical microscopy, Electronic microscopy - only SEM, TEM and X-ray diffraction (Principle and Applications only) <b>Macroscopy:</b> Sulphur printing, flow line observation, spark test		
<b>Unit III</b>	<b>Phase Diagrams and Iron-Carbon Diagram</b>	<b>[09 Hr.]</b>
<b>Solid solutions:</b> Introduction, Types, Hume-rothery rule for substitutional solid solutions <b>Solidification:</b> Nucleation & crystal growth, solidification of pure metals, solidification of alloys. <b>Phase Diagrams:</b> Cooling curves, types of phase diagrams, Gibbs phase rules. <b>Iron-Carbon Diagram:</b> Iron-carbon equilibrium diagrams in detail with emphasis in the invariant reactions.		

<b>Unit IV</b>	<b>Heat Treatments</b>	<b>[08 Hr.]</b>
<p><b>Austenite transformation in steel:</b> Time temperature transformation diagrams, continuous cooling transformation diagrams. Retained austenite and its effect</p> <p>Steps in Heat treatment and Cooling Medium</p> <p><b>Heat Treatment Processes:</b> Introduction, Annealing (Full annealing, Process annealing, Spheroidise annealing, isothermal annealing, stress relief annealing), Normalising, Hardening, Tempering, Austempering, Martempering, Sub-Zero Treatment, Hardenability</p> <p><b>Surface Hardening:</b> Classification, Flame hardening, Induction hardening, Carburising, Nitriding, Carbonitriding</p>		
<b>Unit V</b>	<b>Ferrous Materials</b>	<b>[07 Hr.]</b>
<p><b>Carbon Steel:</b> Classification, types &amp; their composition, properties and Industrial application</p> <p><b>Alloy Steels:</b> Classification of alloy steels &amp; Effect of alloying elements, examples of alloy steels, (Stainless steel, Tool steel) sensitization of stainless steel</p> <p><b>Designation</b> of carbon steel and alloy steels as per IS, AISI, SAE Standards</p> <p><b>Cast Iron:</b> Classification, types &amp; their composition, properties and Industrial application of (White CI, Gray CI, SG CI, Malleable Cast and alloy Cast Iron)</p> <p>Microstructure and property relationship of various ferrous Materials</p>		
<b>Unit VI</b>	<b>Non-Ferrous Materials</b>	<b>[07 Hr.]</b>
<p><b>Classification of Non-Ferrous Metals:</b> Study of Non-ferrous alloys with Designation, Composition, Microstructure</p> <p><b>Mechanical &amp; other properties for Industrial Applications:</b> Copper and its Alloys (Gilding Metal, Cartridge Brass, Muntz Metal, Tin Bronze, Beryllium Bronze), Aluminium and its Alloy (LM5, Duralumin, Y-Alloy, Hinduminium), Nickel and its Alloys (Invar, Inconel), Titanium and its Alloys (<math>\alpha</math> Alloys, <math>\alpha</math>-<math>\beta</math> Alloys), Cobalt and its Alloys (Stellite Alloys, Alnico), Bearing Alloys (Classification, lead based alloys, tin based alloys), Age Hardening</p> <p>Microstructure and Property relationship of various Non-ferrous Materials</p> <p><b>Recent Material used in Additive Manufacturing:</b> Properties, Composition and Application only</p>		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
<ol style="list-style-type: none"> <li>1. Dr. V. D. Kodgire &amp; S. V. Kodgire, "Material Science &amp; Metallurgy For Engineers", Everest Publication.</li> <li>2. William D. Callister, "Materials Science and Engineering an Introduction", Jr, John Wiley &amp; Sons, Inc.</li> </ol>		
<b>Reference Books</b>		
<ol style="list-style-type: none"> <li>1. A. K. Bhargava, C.P. Sharma, "Mechanical Behaviour &amp; Testing of Materials", P H I Learning Private Ltd.</li> <li>2. Raghvan V., "Material Science &amp; Engineering", Prentice Hall of India, New Delhi. 2003</li> <li>3. Avner, S.H., "Introduction to Physical Metallurgy", Tata McGraw-Hill, 1997.</li> <li>4. Higgins R. A., "Engineering Metallurgy", Viva books Pvt. Ltd.</li> </ol>		
<b>Guidelines for Laboratory Conduction</b>		
The student shall complete the following activity as a Term Work Journal		
<p><i>Total 10 experiments from the following list must be performed. Term Work of the Student is evaluated based on the completion of Practical, Assignments, and Industrial Visits.</i></p> <p><b>Practical (Any Seven)</b></p> <ol style="list-style-type: none"> <li>1. Destructive testing - Hardness testing (Rockwell/Vickers) Hardness conversion number</li> <li>2. Brinell and Poldi hardness Test</li> <li>3. Impact Test for Steel, Aluminum, Brass and Copper (Charpy/Izod)</li> </ol>		

4. Non Destructive testing - Dye Penetrant Test/ Magnetic Particle test/ Ultrasonic Test
5. Steps for Specimen Preparation for microscopic examination & Demonstration of Optical Metallurgical microscope
6. Observation and Drawing of Microstructure of Steels, Cast Iron of various compositions
7. Observation and Drawing of Microstructure of Non Ferrous Metals of various compositions
8. Heat Treatment of steels based on relative hardness
9. Jominy End Quench Test for hardenability

**Miniature commitment or Assignments** (*Any Two*)

1. Exploration of engineering Alloy (Name, composition, properties, microstructure, Heat treatment, Designation & specific applications) - One student one Alloy or material
2. Examine aspects of component form material and manufacturing process point of view (Name, Material, Drawing, Manufacturing Process, properties, microstructure, Heat treatment, & specific applications) - For example spur gear, Needle etc. One student one component
3. Creep and Fatigue Test (Virtual Lab IIT Bombay)
4. Fluorescence Microscope (Virtual Lab IIT Bombay)

**Industrial Visits**

*To provide awareness and understanding of the course, Compulsory Industrial Visit must be arranged for the students.*

The Industrial Visit must be preferably to

- Material & Metallurgy related like Engineering Cluster, NDT Lab, and Nearby NABL lab or
- Any manufacturing unit with material orientation

Student must submit a properly documented Industrial Visit Report.

**Guidelines for Instructor’s Manual**

The Instructor’s Manual should contain following related to every experiment:

1. Brief theory related to the experiment
2. Apparatus with their detailed specifications
3. Standard ASME/ IS numbers of test procedure
4. Schematic, Layout/diagram
5. Observation table/graphs.
6. Sample calculations for one/two reading
7. Result table, Graph and Conclusions.
8. 3/4 questions related to the experiment
9. Relevance of practical in industry with recent software of image analysis

**Guidelines for Student’s Lab Journal**

The Student's Lab Journal should contain following related to every experiment:

1. Theory related to the experiment
2. Apparatus with their detailed specifications
3. Schematic, Layout/diagram
4. Observation table/simulation plots/graphs
5. Sample calculations for one/two reading
6. Result table. Graph and Conclusions
7. 3/4 questions related to the experiment
8. Attach Photo of experiment or image related to Experiment

**Guidelines for Lab/TW Assessment**

1. There should be continuous assessment for the TW
2. Assessment must be based on understanding of theory, attentiveness during practical, and understanding
3. Session, how efficiently the student is able to do connections and get the results
4. Online evolutions of practical with objective type of Questions
5. Timely submission of journal

<b>202521 - Electrical Technology</b>		
<b>Teaching Scheme</b>	<b>Credits</b>	<b>Examination Scheme</b>
Theory : 03 Hr./Week Practical : 02 Hr./Week	<b>04</b> Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Oral : 25 Marks
<b>Prerequisite Courses</b> 103004- Basic Electrical Engineering, 102003-Systems in Mechanical Engineering		
<b>Course Objectives</b> 1. The constructional details, characteristics, features and speed control methods of DC motors. 2. The constructional details, equivalent circuit and applications of transformers in robotics and automation 3. Principle of operation, types, speed-torque characteristics of induction motor 4. Construction and working principle and applications of special machines 5. Structure of electric power systems and substation layout 6. Modeling of physical systems and transfer function		
<b>Course Outcomes</b> On completion of the course, learner will be able to CO1: Explain the construction, working and applications of DC machines CO2: Understand the construction, equivalent circuit and applications of transformers CO3: Explain the construction, operation, types and applications of induction motors CO4: Understand the construction, working principle, applications and sizing of special motors CO5: Explain the structure of electric power systems and EHV transmission systems CO6: Understand the modeling of physical systems and transfer function of various components		
<b>Course Contents</b>		
<b>Unit I</b>	<b>DC Machines</b>	<b>[08 Hr.]</b>
Electromechanical energy conversion, Rotating machines, Driving and opposing torque, Faradays law, Generator mode and Motor mode, Constructional details of DC Machines, EMF equation, Methods of excitation, Self and separately excited Shunt generator, Principle of operation of DC Motor, Back emf and torque equation, Characteristics of DC series and shunt motors, Starting of DC Motors, Need for Starters, Speed control and Braking of DC motors (Voltage Control & Dynamic Braking Only), Principle of Brushless DC motors, Direct Drive High Torque Motors.		
<b>Unit II</b>	<b>Transformers</b>	<b>[07 Hr.]</b>
Constructional Details, Principle of Operation, EMF Equation, Transformation ratio. Transformer on no load, Parameters referred to HV/LV windings – Equivalent circuit – Dot Convention - Transformer on load – Regulation - Losses and efficiency - Load test – Three phase transformers connections. Introduction to Current and Potential Transformers, Applications of Transformer in Robotics and Automation		
<b>Unit III</b>	<b>Induction Motors</b>	<b>[08 Hr.]</b>
Construction, Types, Principle of operation of three phase induction motors, Speed Torque characteristics, Equivalent circuit, Starting and Speed control, Single-phase induction motors (only qualitative analysis). Introduction to Linear induction motor, PMSIM, Applications		
<b>Unit IV</b>	<b>Synchronous and Special Machines</b>	<b>[07 Hr.]</b>
Construction of Synchronous machines - Types, Induced EMF, Working principles of: Brushless alternators, Stepper motor, Servomotor, Universal motor. Applications, rating and duty cycle, Sizing of Motor for an industrial application.		

<b>Unit V</b>	<b>Power Systems</b>	<b>[08 Hr.]</b>
Introduction, Structure of electric power systems – Generation, transmission, sub-transmission and distribution systems, EHVAC and EHVDC transmission systems, Substation layout. (Concepts only).		
<b>Unit VI</b>	<b>Automatic Control Systems</b>	<b>[07 Hr.]</b>
Components of Automatic control systems - Open loop and closed loop systems, Transfer function, Modeling of physical systems, Mechanical Systems - Translational and Rotational systems, Thermal, Hydraulic systems and Electrical Systems, Transfer function of DC servomotor, AC servomotor, Potentiometer, Tacho-generator, Stepper motor – Block diagram, reduction techniques, Signal flow graph – Mason’s gain formula		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
<ol style="list-style-type: none"> <li>1. K Murugesh Kumar, —DC Machines and Transformers, Vikas Publishing House Pvt Ltd, 2010.</li> <li>2. K Murugesh Kumar, —Induction and Synchronous machines, Vikas Publishing House Pvt Ltd, 2010.</li> <li>3. Edward Hughes “Electrical Technology”, ELBS, Pearson Education.</li> <li>4. Ashfaq Husain, “Electrical Machines”, Dhanpat Rai &amp; Sons.</li> <li>5. S. K. Bhattacharya, “Electrical Machine”, Tata Mc Graw Hill publishing Co. Ltd, 2nd Edition.</li> <li>6. Nagrath &amp; Kothari, “Electrical Machines”, Tata Mc Graw Hill publishing Co. Ltd.</li> </ol>		
<b>Reference Books</b>		
<ol style="list-style-type: none"> <li>1. Haruhiko Asada, Kamal Youeef-Toumi, —Direct-Drive Robots Theory and Practice, The MIT Press, Cambridge, 1987</li> <li>2. Electrical Machines, Lowe, Nelson Publications.</li> <li>3. A.E. Fitzgerald, Charles Kingsley, Stephen D. Umans, “Electrical Machines”, Tata McGraw Hill Publication Ltd. Fifth Edition.</li> <li>4. Permanent Magnet Synchronous and Brushless DC Motor Drives, R. Krishnan, CRC press.</li> <li>5. Smarajit Ghosh, “Electrical Machines”, Pearson Education, New Delhi.</li> </ol>		
<b>Guidelines for Laboratory Conduction</b>		
<p>The student shall perform any 8 of the following:</p> <ol style="list-style-type: none"> <li>1. Speed control of DC shunt motor</li> <li>2. Brake test on DC shunt motor</li> <li>3. OC and SC tests on single phase transformer</li> <li>4. Determination of equivalent circuit parameters of three phase induction motor by no-load and blocked rotor test</li> <li>5. Load test on 3 phase induction motor</li> <li>6. Plotting speed-torque characteristic of three phase induction motor</li> <li>7. Determination of equivalent circuit parameters of single phase induction motor by no-load and blocked rotor test</li> <li>8. Study of starters for AC and DC motors</li> <li>9. Study of BLDC motor drive</li> <li>10. Study of operating modes of stepper motor</li> </ol>		
<b>Guidelines for Lab/TW/PR Assessment</b>		
<ol style="list-style-type: none"> <li>1. Continuous assessment should be carried out time to time.</li> <li>2. During assessment, faculty should put the remark by writing the word “Complete” and not simply “C”. Put the signature along with the date at the end of experiment and also in the index.</li> <li>3. Assess each laboratory experiment/virtual lab assignment/report of industrial visit/case study for 10 marks each as per following details: Attendance in practical - 02 marks Timely completion of journal -03 marks Presentation of write-up and results - 02 marks Depth of understanding - 03 marks</li> <li>4. Maintain a continuous assessment sheet on the basis of which final TW marks can be offered.</li> </ol>		

**202522 – Industrial Electronics**

Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	04 Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Term Work : 25 Marks

**Prerequisite Courses**

Basic Electrical Engineering, Systems in Mechanical Engineering

**Course Objectives:**

1. To provide knowledge levels needed for automation using PLC
2. To make the students understand how devices are connected with PLC input and output modules.
3. To train the students to create ladder diagrams from process control descriptions.
4. To make the students understand HMI Systems & PLC Networking
5. To apply PLC Timers and Counters for the control of industrial processes
6. To make the students understand PLC functions, Data Handling Function

**Course Outcomes**

On completion of the course, learner will be able :

CO1: To explain the different applications of Programmable Logic Controllers

CO2: To Identify different types of Devices to which PLC input and output modules are connected

CO3: To create ladder diagrams from process control descriptions

CO4: To use HMI Systems & PLC Networking

CO5: To use different types PLC functions, Data Handling Function

CO6: To classify different applications of Programmable Logic Control

**Course Contents**

**Unit I Factory & Process Automation [07 Hr.]**

Introduction, Industrial Versions - Control elements of Industrial Automation, IEC/ ISA Standards for Control Elements, Selection criteria for control elements, Construction of Relay Ladder logic with different control elements, Need for PLC, PLC evolution, PLC input/output instructions, Development of Relay ladder logic, Ladder programming for logic gates & Boolean algebra, Ladder diagram

**Unit II Programmable Logic Controllers [07 Hr.]**

Introduction, Architecture of PLC - Types of PLC, PLC modules, PLC Configuration, Scan cycle, Capabilities of PLC, Selection criteria for PLC, PLC Communication with PC and software, PLC Wiring, Installation of PLC and its modules, Interfacing of I/O devices to PLC

**Unit III Programming of PLC [07 Hr.]**

Introduction, Types of Programming, Bit Instructions, Timers and counters, PLC arithmetic functions PTO / PWM generation, High Speed Counter, Analog Scaling, Encoder Interfacing, Servo drive control, Stepper Motor Control, Applications of PLC

**Unit IV HMI Systems & Networking [07 Hr.]**

Introduction, Need for HMI in Industrial Automation, Types of HMI – Configuration of HMI, Screen development and navigation, Configuration of HMI elements / objects and Interfacing with PLC, Advantages of using HMI.

PLC Networking- Networking standards & IEEE Standard, Protocols, Field bus, Process bus and Ethernet, CAN Open.

**Unit V Manufacturing & Process Automation [07 Hr.]**

Introduction, Batch control description and terminology, Batch processes and automation, Blending and ratio control, pH control, Fan / Compressor / Pump Control, Extruder control, etc.

Case studies of manufacturing automation and Process automation.

<b>Unit VI</b>	<b>Digital Logic Families</b>	<b>[07 Hr.]</b>
Introduction, Characteristics of digital ICs, Voltage and current ratings, Noise margin, Propagation delay, Power dissipation. TTL logic family – Totem pole, Open collector and tristate outputs. MOS transistor switches, nMOS Inverter / Logic gates, CMOS logic, Inverter / logic gates, ECL logic families – Comparison of performance of various logic families		
<b>Books &amp; Other Resources</b>		
<b>Text Books:</b>		
1. Gary Dunning, ‘Introduction to Programmable Logic Controllers‘ Thomson Learning, 2001.		
2. Bolton , "Programmable Logic Controllers" 5th Edition Newnes, ,2009		
<b>Reference Books:</b>		
1. Parr, "Programmable Controllers: An Engineers Guide", 3rd Edition, Elsevier, Indian Reprint, 2013		
2. Muhammad Ali Mazdi, J.G.Mazdi & R.D. McKinlay “The 8051 Microcontroller& Embedded systems Using assembly & C “2nd Edition Pearson Education, Inc ,2006.		
3. John R Hackworth and Fredrick D Hackworth Jr., Programmable Logic Controllers: Programming Methods and Applications, Pearson Education, 2015.		
<b>Guidelines for Laboratory Conduction</b>		
The student shall perform any 8 of the following:		
1. Development of ladder logic diagram using Bit Instructions.		
2. PLC based Crane control.		
3. PLC based parking station using Counter and Bit Instructions.		
4. Analog Sensor interfacing with PLC.		
5. Encoder interfacing with PLC.		
6. Stepper motor / Servo motor control using PLC.		
7. Control the lift using programmable logic controller		
8. Control the traffic signals using PLC		
9. Implement the up down counter using PLC		
10. Implement the digital clock using PLC		
11. Control the temperature of a system using PLC		
12. Identify and integrate the components of SCADA and HMI.		

## 202045 - Geometric Dimensioning and Tolerancing Lab

Teaching Scheme	Credits	Examination Scheme
Practical : 02 Hr./Week	<b>01</b> Practical : 01	Term Work : 25 Marks

### Prerequisite Courses

Systems in Mechanical Engineering, Project Based Learning - I, Workshop Practice, Engineering Graphics

### Course Objectives

1. To understand requirements of industrial drawings
2. To read, understand and explain basic Geometric Dimensioning & Tolerancing concepts
3. To apply various geometric and dimension tolerances based on type of fit
4. To include surface roughness symbols based on manufacturing process
5. To measure and verify position tolerances with applied material conditions
6. To understand requirements for manufacturing and assembly

### Course Outcomes

On completion of the course, learner will be able to

- CO1. SELECT appropriate IS and ASME standards for drawing
- CO2. READ & ANALYSE variety of industrial drawings
- CO3. APPLY geometric and dimensional tolerance, surface finish symbols in drawing
- CO4. EVALUATE dimensional tolerance based on type of fit, etc.
- CO5. SELECT an appropriate manufacturing process using DFM, DFA, etc.

### Guidelines for Laboratory Conduction

The student shall complete the following activity as a Term Work Journal

*Total 9 Practical Assignments from the following list must be performed. Term Work of the Student is evaluated based on the completion of Practical, Industrial Visit Report and Group Assignment.*

**Practical** (Assignment # 1 to 6 & 10 are compulsory; Select any Two from Assignment # 7 to 9)

*The student shall complete the following Practical in laboratory. Learner will demonstrate skills to communicate drawings as per industry standards:*

1. Study of drawing sheet layout, Principles of Drawing and various IS Standards & Conventions in Machine Drawing, Dimensioning practices - Terminology & Basic Rules, Styles, Conventions [02 Hr.]
2. GD&T -
  - (a) Terminology, Maximum and Minimum Material conditions, Features, Rules for GD&T, Datum Control [02 Hr.]
  - (b) Adding GD&T to a Design, Form Tolerances [02 Hr.]
  - (c) Orientation Tolerances, Profile Tolerances [02 Hr.]
  - (d) Location Tolerances, Run out Tolerances [02 Hr.]
3. Surface finish, Welding symbols [02 Hr.]
4. Study and reading of Industrial Drawings to understand standard industrial practices viz. Dimensioning, GD&T, Surface finish, welding symbols, etc. [04 Hr.]
  - (a) Machine Drawing, (b) Production Drawing, (c) Part Drawing,
  - (d) Assembly Drawing - (i) Assembly Drawing for Design, (ii) Assembly Drawing for Instruction Manuals, (iii) Exploded Assembly Drawing, (iv) Schematic Assembly Drawing, (v) Patent Drawing, etc.
5. Calculation of Tolerances based on Type of Fits in Assembly [02 Hr.]
6. Tolerance Stacks-Up with suitable examples [02 Hr.]
7. Design for Manufacturing (DFM) with suitable examples [02 Hr.]
8. Design for Assembly and Dis-assembly with suitable examples [02 Hr.]



9. Design for Safety with suitable examples	[02 Hr.]
10. Industrial visit / Case study	
<b>Books &amp; Other Resources</b>	
<b>Text Books</b>	
1. Standards: ASME Y14.5 – 2018	
2. Narayana, K. L., Kanniah, P., Venkata Reddy, K., (2016), “Machine Drawing”, 2 <sup>nd</sup> edition, New Age International Publishers, New Delhi, India, ISBN-13: 978-8122440546	
3. Bhatt, N. D. and Panchal, V. M., (2014), “Machine Drawing”, Charotar Publishing House Pvt. Ltd, Anand, India, ISBN-13: 978-9385039232	
<b>Reference Books</b>	
1. Cogorno, G. R., (2020), "Geometric Dimensioning and Tolerancing for Mechanical Design", 3 <sup>rd</sup> edition, McGraw-Hill Education	
2. Blokdyk, Gerardus, (2019), "Geometric Dimensioning and Tolerancing: A Complete Guide - 2020 Edition", 5STARCOoks	
3. Standards: ISO/TR 23605:2018, ISO 1101:2017, SP 46, IS 15054(2001)	

**202046 - Audit Course - III**

Teaching Scheme	Credits	Examination Scheme
-	-	-

**GUIDELINES FOR CONDUCTION OF AUDIT COURSE**

**Faculty mentor shall be allotted for individual courses and he/she shall monitor the progress for successful accomplishment of the course. Such monitoring is necessary for ensuring that the concept of self-learning is being pursued by the students ‘in true letter and spirit’.**

- If any course through Swayam/NPTEL/virtual platform is selected the minimum duration shall be of 8 weeks.
- However if any of the course duration is less than the desired (8 weeks) the mentor shall ensure that other activities in form of assignments, quizzes, group discussion etc. (allied with the course) for the balance duration should be undertaken.

In addition to credits courses, it is mandatory that there should be an audit course (non-credit course) from second year of Engineering. The student will be awarded grade as AP on successful completion of the audit course. The student may opt for any one of the audit courses in each semester. Such audit courses can help the student to get awareness of different issues which make an impact on human lives and enhance their skill sets to improve their employability. List of audit courses offered in the semester is provided in the curriculum. Students can choose one of the audit courses from the list of courses mentioned. Evaluation of the audit course will be done at institute level.

The student registered for audit course shall be awarded the grade AP and shall be included such grade in the Semester grade report for that course, provided student has the minimum attendance as prescribed by the Savitribai Phule Pune University and satisfactory in-semester performance and secured a passing grade in that audit course. No grade points are associated with this 'AP' grade and performance in these courses is not considered in the calculation of the performance indices SGPA and CGPA. Evaluation of the audit course will be done at institute level itself.

**Selecting an Audit Course****List of Courses to be opted (Any one) under Audit Course III**

- Technical English For Engineers
  - Entrepreneurship Development
  - Developing soft skills and personality
  - Design Thinking
  - Foreign Language (preferably German/ Japanese)
  - Science, Technology and Society
- # The titles indicated above are subject to change in time to come and such an alteration (if any) should be brought to the notice of the BoS.

**Using NPTEL Platform: (preferable)**

NPTEL is an initiative by MHRD to enhance learning effectiveness in the field of technical education by developing curriculum based video courses and web based e-courses. The details of NPTEL courses are available on its official website [www.nptel.ac.in](http://www.nptel.ac.in)

- Students can select any one of the courses mentioned above and has to register for the corresponding online course available on the NPTEL platform as an Audit course.
- Once the course is completed the student can appear for the examination through NPTEL portal.
- After clearing the examination successfully; student will be awarded with a certificate.

**Assessment of an Audit Course**

- The assessment of the course will be done at the institute level. The institute has to maintain the record of the various audit courses opted by the students.
- During the course students will be submitting the online assignments. A copy of the same can be submitted as a part of term work for the corresponding Audit course.
- On the satisfactory submission of assignments, the institute can mark as “Present” and the student will be awarded the grade AP on the marksheet.

**207002 - Engineering Mathematics - III**

Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Tutorial : 01Hr/Week	04 Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Term Work : 25 Marks

**Prerequisite Courses**

Differential & Integral calculus, Differential equations of first order & first degree, Fourier series, Collection, classification and representation of data and Vector algebra.

**Course Objectives**

- To make the students familiarize with concepts and techniques in Ordinary & Partial differential equations, Laplace transform & Fourier transform, Statistical methods, Probability theory and Vector calculus.
- The aim is to equip them with the techniques to understand advanced level mathematics and its applications that would enhance analytical thinking power, useful in their disciplines.

**Course Outcomes**

On completion of the course, learner will be able to

- CO1. SOLVE higher order linear differential equations and its applications to model and analyze mass spring systems.
- CO2. APPLY Integral transform techniques such as Laplace transform and Fourier transform to solve differential equations involved in vibration theory, heat transfer and related mechanical engineering applications.
- CO3. APPLY Statistical methods like correlation, regression in analyzing and interpreting experimental data applicable to reliability engineering and probability theory in testing and quality control.
- CO4. PERFORM Vector differentiation & integration, analyze the vector fields and APPLY to fluid flow problems.
- CO5. SOLVE Partial differential equations such as wave equation, one and two dimensional heat flow equations.

**Course Contents**

**Unit I Linear Differential Equations (LDE) and Applications [08 Hr.]**

LDE of nth order with constant coefficients, Complementary Function, Particular Integral, General method, Short methods, Method of variation of parameters, Cauchy's and Legendre's DE, Simultaneous and Symmetric simultaneous DE. Modelling of Mass-spring systems, Free & Forced damped and undamped systems.

**Unit II Transforms [08 Hr.]**

Laplace Transform (LT): LT of standard functions, properties and theorems, Inverse LT, Application of LT to solve LDE.

Fourier Transform (FT): Fourier integral theorem, Fourier transform, Fourier sine & cosine transforms, Inverse Fourier Transforms.

**Unit III Statistics [07 Hr.]**

Measures of central tendency, Measures of dispersion, Coefficient of variation, Moments, Skewness and Kurtosis, Curve fitting: fitting of straight line, parabola and related curves, Correlation and Regression, Reliability of Regression Estimates.

**Unit IV Probability and Probability Distributions [07 Hr.]**

Probability, Theorems on Probability, Bayes Theorem, Random variables, Mathematical Expectation, Probability distributions: Binomial, Poisson, Normal, Test of Hypothesis: Chi-Square test, t-test.

**Unit V Vector Calculus [08 Hr.]**

Vector differentiation, Gradient, Divergence and Curl, Directional derivative, Solenoidal & Irrotational fields, Vector identities. Line, Surface and Volume integrals, Green's Lemma, Gauss's Divergence theorem and Stoke's theorem.

<b>Unit VI</b>	<b>Applications of Partial Differential Equations (PDE)</b>	<b>[08 Hr.]</b>
Basic concepts, modelling of Vibrating String, Solution of Wave equation, One and two dimensional Heat flow equations, Method of separation of variables, use of Fourier series. Solution of Heat equation by Fourier transforms.		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
1. B.V. Ramana, “Higher Engineering Mathematics”, Tata McGraw-Hill		
2. B. S. Grewal, “Higher Engineering Mathematics”, Khanna Publication, Delhi		
<b>Reference Books</b>		
1. Erwin Kreyszig, “Advanced Engineering Mathematics’, 10e, by Wiley India.		
2. M. D. Greenberg, “Advanced Engineering Mathematics”, 2e, by Pearson Education.		
3. Peter V. O’Neil , “Advanced Engineering Mathematics”, 7e, by Cengage Learning		
4. S. L. Ross, “Differential Equations”, 3e by Wiley India.		
5. Sheldon M. Ross, “Introduction to Probability and Statistics for Engineers and Scientists”, 5e, by Elsevier Academic Press		
<b>Guidelines for Tutorial and term Work</b>		
1. Tutorial shall be engaged in four batches (batch size of 20 students maximum) per division.		
2. Term work shall be based on continuous assessment of six assignments (one per each unit) and performance in internal tests. The student shall complete the following activity as a Term Work Journal.		

202047 - Kinematics of Machinery		
Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	<b>04</b> Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Oral : 25 Marks
<b>Prerequisite Courses</b> Systems in Mechanical Engineering, Engineering Mathematics - I and II, Engineering Physics, Engineering Mechanics, Geometric Modeling & Drafting		
<b>Course Objectives</b> 1. To make the students conversant with kinematic analysis of mechanisms applied to real life and industrial applications. 2. To develop the competency to analyze the velocity and acceleration in mechanisms using analytical and graphical approach. 3. To develop the skill to propose and synthesize the mechanisms using graphical and analytical technique. 4. To develop the competency to understand & apply the principles of gear theory to design various applications. 5. To develop the competency to design a cam profile for various follower motions.		
<b>Course Outcomes</b> On completion of the course, learner will be able to CO1. APPLY kinematic analysis to simple mechanisms CO2. ANALYZE velocity and acceleration in mechanisms by vector and graphical method CO3. SYNTHESIZE a four bar mechanism with analytical and graphical methods CO4. APPLY fundamentals of gear theory as a prerequisite for gear design CO5. CONSTRUCT cam profile for given follower motion		
<b>Course Contents</b>		
<b>Unit I</b>	<b>Fundamentals of Mechanism</b>	<b>[07 Hr.]</b>
Kinematic link, Types of links, Kinematic pair, Types of constrained motions, Types of Kinematic pairs, Kinematic chain, Types of joints, Mechanism, Machine, Degree of freedom, Mobility of Mechanism, Inversion, Grashoff's law, Four-Bar Chain and its Inversions, Slider crank Chain and its Inversions, Double slider crank Chain and its Conversions, Mechanisms with Higher pairs, Equivalent Linkages and its Cases - Sliding Pairs in Place of Turning Pairs, Spring in Place of Turning Pairs, Cam Pair in Place of Turning Pairs		
<b>Unit II</b>	<b>Kinematic Analysis of Mechanisms: Analytical Method</b>	<b>[07 Hr.]</b>
Analytical methods for displacement, velocity and acceleration analysis of slider crank Mechanism, Velocity and acceleration analysis of Four-Bar and Slider crank mechanisms using Vector and Complex Algebra Methods. Computer-aided Kinematic Analysis of Mechanism like Slider crank and Four-Bar mechanism, Analysis of Single and Double Hook's joint		
<b>Unit III</b>	<b>Kinematic Analysis of Mechanisms: Graphical Method</b>	<b>[08 Hr.]</b>
Displacement, velocity and acceleration analysis mechanisms by Relative Velocity Method (Mechanisms up to 6 Links), Instantaneous Centre of Velocity, Kennedy's Theorem, Angular Velocity ratio Theorem, Analysis of mechanism by ICR method (Mechanisms up to 6 Links), Coriolis component of Acceleration (Theoretical treatment only)		
<b>Unit IV</b>	<b>Synthesis of Mechanisms</b>	<b>[07 Hr.]</b>
<b>Steps in Synthesis:</b> Type synthesis, Number Synthesis, Dimensional synthesis, Tasks of Kinematic synthesis - Path, function and motion generation (Body guidance), Precision Positions, Chebychev spacing, Mechanical and structural errors <b>Graphical Synthesis:</b> Inversion and relative pole method for three position synthesis of Four-Bar and Single Slider Crank Mechanisms		

**Analytical Synthesis:** Three position synthesis of Four-Bar mechanism using Freudenstein's equation, Blotch synthesis

**Unit V** **Kinematics of Gears** **[08 Hr.]**

**Gear:** Classification

**Spur Gear:** Terminology, law of gearing, Involute and cycloidal tooth profile, path of contact, arc of contact, sliding velocity, Interference and undercutting, Minimum number of teeth to avoid interference, Force Analysis (theoretical treatment only)

**Helical and Spiral Gears:** Terminology, Geometrical Relationships, virtual number of teeth for helical gears

**Bevel Gear & Worm and Worm Wheel:** Terminology, Geometrical Relationships

**Gear Train:** Types, Analysis of Epicyclic gear Trains, Holding torque - simple, compound and Epicyclic gear Trains, Torque on Sun and Planetary gear Train, compound Epicyclic gear Train

**Unit VI** **Mechanisms in Automation Systems** **[08 Hr.]**

**Cams & Followers:** Introduction, Classification of Followers and Cams, Terminology of Cam Displacement diagram for the Motion of follower as Uniform velocity, Simple Harmonic Motion (SHM), Uniform Acceleration and Retardation Motion (UARM), Cycloid motion, Cam Profile construction for Knife-edge Follower and Roller Follower, Cam jump Phenomenon

**Automation:** Introductions, Types of Automation

**Method of Work Part Transport:** Continuous transfer, Intermittent or Synchronous Transfer, Asynchronous transfer, Different type of transfer mechanisms - Linear transfer mechanisms and Rotary transfer mechanisms

**Automated Assembly-Line:** Types, Assembly line balancing Buffer Storages, Automated assembly line for car manufacturing, Artificial intelligence in automation

#### **Books & Other Resources**

##### **Text Books**

1. S. S. Rattan, "Theory of Machines", Third Edition, McGraw Hill Education (India) Pvt. Ltd., New Delhi.
2. Bevan T, "Theory of Machines", Third Edition, Longman Publication
3. G. Ambekar, "Mechanism and Machine Theory", PHI
4. J. J. Uicker, G. R. Pennock, J. E. Shigley, "Theory of Machines and Mechanisms", Fifth Edition, International Student Edition, Oxford

##### **Reference Books**

1. Paul E. Sandin, "Robot Mechanisms and Mechanical Devices Illustrated", Tata McGraw Hill Publication
2. Stephen J. Derby, "Design of Automatic Machinery", 2005, Marcel Dekker, New York
3. Neil Sclater, "Mechanisms and Mechanical Devices Sourcebook", Fifth Edition, Tata McGraw Hill Publication
4. Ghosh Malik, "Theory of Mechanism and Machines", East-West Pvt. Ltd.
5. Hannah and Stephans, "Mechanics of Machines", Edward Arnold Publication
6. R. L. Norton, "Kinematics and Dynamics of Machinery", First Edition, McGraw Hill Education (India) P Ltd. New Delhi
7. Sadhu Singh, "Theory of Machines", Pearson
8. Dr. V. P. Singh, "Theory of Machine", Dhanpatrai and Sons
9. C. S. Sharma & Kamlesh Purohit, "Theory of Machine and Mechanism", PHI
10. M.P. Groover, "Automation, production systems and computer-integrated manufacturing", Prentice-Hall of India Pvt. Ltd, New Delhi

##### **Web References**

1. <https://nptel.ac.in/courses/112104121/> (NPTEL1, Kinematics of Machines, Prof. Ashok K Mallik, IIT Kanpur)

2. <https://nptel.ac.in/courses/112/106/112106270/> (NPTEL2, Theory of Mechanism, Prof. Sujatha Srinivasan, IIT Madras)
3. <https://nptel.ac.in/courses/112/105/112105268/> (NPTEL3, Kinematics of Mechanisms and Machines, Prof. Anirvan Das Gupta, IIT Kharagpur)
4. <https://nptel.ac.in/courses/112/105/112105236/> (NPTEL4, Mechanism and Robot Kinematics, Prof. Anirvan Das Gupta, IIT Kharagpur)
5. [http://www.cdeep.iitb.ac.in/webpage\\_data/nptel/Mechanical/Robotics/Course/Course\\_home\\_lect1.html](http://www.cdeep.iitb.ac.in/webpage_data/nptel/Mechanical/Robotics/Course/Course_home_lect1.html) (NPTEL5, Introduction to Robotics and Automation, IIT Bombay)

### **Guidelines for Laboratory Conduction**

The student shall complete the following activity as a Term Work

*Total 10 experiments from the following list must be performed. Term Work of the Student is evaluated based on the completion of Practical, Assignments using Drawing Aids, Assignments using Software & Programming Languages, Assignments using Virtual Laboratory and Detailed Industrial Visit Report.*

**Practical** (*Experiment # 1 is compulsory and Select any Two from Experiment # 2 to 4*)

1. To make a model of any mechanism by using waste material by the group of 4 to 6 students and to give a presentation using PPTs.
2. Speed and torque analysis of epicyclic gear train to determine holding torque.
3. To study and verify cam jump phenomenon.
4. To study manufacturing of gear using gear generation with rack as a cutter and to generate an involute profile.

**Assignments using Drawing Aids** (*Experiment #1 to 3 and 6 are compulsory and Select any One from Experiment #4-5*)

Do following graphical assignments on Half Imperial drawing sheet:

1. Identify mechanisms in real life and Analyze for types and number of links, pairs, obtain degrees of freedom. Submit the sheet and working video of the mechanism.
2. To solve two problems on velocity and acceleration analysis using relative velocity and acceleration method.
3. To solve two problems on velocity analysis using the ICR method.
4. To draw conjugate profile for any general type of gear tooth.
5. To study various types of gearboxes.
6. To draw cam profile for any two problems with combination of various follower motion with radial and off-set cam.

**Assignments using Software** (*Any Three Assignments - Minimum one computer programming based and Minimum one based on use of software*)

Do following assignments by using Software or by using Coding/Programming Languages:

1. To design a simple Planer Mechanism by using any software (Geogebra, SAM, Working Model, any 3D Modelling Software, etc.)
2. To do computer programming (using software/programming languages like C, Python, Scilab, Matlab etc.) for Kinematic Analysis of Slider Crank Mechanism using Analytical Method
3. To do computer programming (using software/programming languages like C, Python, Scilab, Matlab etc.) for Kinematic Analysis of Hooke's joint Mechanism using Analytical Method
4. To generate a Cam Profile using any Modelling Software (MechAnalyser, any 3D Modelling Software)
5. To synthesize the Four-Bar and Slider Crank Mechanism (Geogebra, SAM, any 2D/3D Modelling Software)
6. To do computer programming (using software/programming languages like C, Python, Scilab, Matlab etc.) for the Synthesis of Mechanism using Chebychevs spacing, Freudensteins equation and function generation

**Assignments using Virtual Laboratory** (*minimum Two experiments*)

Please visit the links given below for exploring experiments on Kinematics of Machinery using

Virtual Laboratory. Write a Brief Reports of using Virtual Laboratory to perform following assignment:

1. Mechanics-of-Machines Lab (All Experiments), <http://mm-nitk.vlabs.ac.in/index.html>
2. Mechanisms and Robotics - Oldham Coupling Mechanism, <http://vlabs.iitkgp.ernet.in/mr/index.html>
3. Mechanisms and Robotics - Quick Return Mechanism, <http://vlabs.iitkgp.ernet.in/mr/index.html>
4. Mechanisms and Robotics - CAM Follower Mechanism, <http://vlabs.iitkgp.ernet.in/mr/index.html>

### **Industrial Visits**

*A Compulsory industrial visit must be arranged to industries/ establishments consisting automation and mechanization during semester to provide awareness and understanding of the course.*

The Industrial Visit must be preferably to

- Manufacturing industries with Assembly-line Automation
- Sugar factory
- Bottle filling plants

Student must submit properly documented Detailed Industrial Visit Report in his/her own words.

### **Assignments on Content beyond syllabus**

Following assignments can be attempted:

1. Forward and Inverse Kinematics of 2R/2P/RP/PR Manipulators using Software (Geogebra, Robo Analyser, Vlab, etc.)
2. Kinematic Analysis of 6 DOF Industrial Robot using Software (Robo Analyzer, Vlab, etc.)



**202523 - Fluid & Thermal Engineering**

Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	04 Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Oral : 25 Marks

**Prerequisite Courses**

Systems in Mechanical Engineering, Engineering Materials & Metallurgy,

**Course Objectives**

1. To understand significance of static fluid properties
2. To understand fluid dynamics in hydraulic circuits
3. To estimate and know remedies to reduce fluid flow losses in hydraulic circuits
4. To understand applications of control valves in pneumatic/hydraulic circuits
5. To know working of air compressor and applications of compressed air in pneumatics
6. To know basic heat transfer concepts and effects of heat in mechanical/electronic circuits.

**Course Outcomes**

On completion of the course, learner will be able to

CO1: COMPARE various fluid properties in engineering applications

CO2: APPLY Bernoulli's equation to fluid flow problems

CO3: INTERPRETE and UNDERSTAND issues related to fluid flow losses in hydraulic circuits

CO4: SELECT appropriate control valve in automation circuits

CO5: EXPLAIN working air compressors and USE of compressed air in pneumatic circuits

CO6: UNDRSTAND sources of heat and remedies of heat removal in electronic circuits

**Course Contents**

**Unit I Properties of Fluids [08 Hr.]**

Characteristics of fluids, Mass density, Specific density, specific gravity, Dynamic viscosity, Kinematic viscosity, Surface tension, capillarity, compressibility, Vapour pressure. Fluid Statics: Pascal's law, Pressure at a point, Total pressure, Centre of pressure, Pressure on a plane, Inclined and curved surfaces, Buoyancy, Metacenter and Metacentric height, stability of submerged and floating bodies

**Unit II Introduction of Fluid Kinematics [07 Hr.]**

Types of flows, continuity equation (Cartesian coordinate), velocity and acceleration, visualization of flow field (stream, path and streak Line); Stream function and velocity potential function. (Simple numerical). Fluid Dynamics Euler's equation of motion along a stream line, Derivation of Bernoulli's equation, Applications of Bernoulli's equation, Venturimeter, Orifice meter, Notches, pitot tube (No derivation and numerical for notches and pitot tube).

**Unit III Fluid Dynamics [08 Hr.]**

Flow through Pipes: Darcy-Weisbach equation, major and minor losses, Pipes in series Pipes in parallel and concept of Equivalent Pipe, Siphons, Transmission of Power (no derivations for minor losses).

Internal flow: Laminar and Turbulent flow physics, Velocity and shear stress distribution for laminar flow in a pipe, fixed parallel plates (simple numerical on velocity, pressure gradient and shear stress).

**Unit IV Control Valves [07 Hr.]**

Introduction, Classification of valves – Ball Valve, Butterfly Valve, Digital Valves, Globe Valve, Pinch Valves, Plug Valves, Application & Selection of valves, Noise calculations and reduction, Valve Sizing

Actuators – Digital, Electric, Pneumatic, Hydraulic, Solenoid

<b>Unit V</b>	<b>Air Compressor</b>	<b>[07 Hr.]</b>
<p>Uses of compressed air, classification of compressors, Reciprocating compressor constructional details of single and multistage compressor, computation of work done, isothermal work done, isothermal efficiency, effect of clearance, volumetric efficiency, need of multi-staging, intercooling and after-cooling. Rotary Air Compressor: Basic principles, classification, construction, working of roots, vane, scroll, Centrifugal and axial compressors. (Descriptive treatment only).</p>		
<b>Unit VI</b>	<b>Heat Transfer</b>	<b>[07 Hr.]</b>
<p>Introduction and Basic Concepts: Application areas of heat transfer, Modes and Laws of heat transfer, Three dimensional heat conduction equation in Cartesian coordinates and its simplified equations, thermal conductivity, Thermal diffusivity, Thermal contact Resistance  Thermal Insulation: Types and selection, Economic and cost considerations, Payback period  Introduction to heat pipe, Introduction to electronic cooling - Discussion on active and passive methods.</p>		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
<ol style="list-style-type: none"> <li>1. Sukumar Pati, "Fluid Mechanics and Hydraulics Machines", TATA McGraw Hill.</li> <li>2. Munson, Young and Okiishi, "Fundamentals of Fluid Mechanics", Wiley India</li> <li>3. Modi P. N. and Seth S. M, "Hydraulics and Fluid Mechanics", Standard Book House.</li> <li>4. P.K. Nag, Heat &amp; Mass Transfer, McGraw Hill Education Private Limited.</li> <li>5. M.M. Rathod, Engineering Heat and Mass Transfer, Third Edition, Laxmi Publications.</li> <li>6. V. M. Domkundwar, Heat Transfer, Dhanpat Rai &amp; Co Ltd.</li> </ol>		
<b>Reference Books</b>		
<ol style="list-style-type: none"> <li>1. Kundu, Cohen, Dowling, "Fluid Mechanics", Elsevier India</li> <li>2. Potter Wiggert, "Fluid Mechanics", Cengage Learning</li> <li>3. Fox, Pichard, "Introduction to Fluid Mechanics", McDonald- Wiley</li> <li>4. Bela G. Liptak, Instrument Engineers' Handbook – Process Control and Optimization, Volume I &amp; II, Taylor &amp; Francis</li> <li>5. Franck P. Incropera, David P. DeWitt – Fundamentals of Heat and Mass Transfer,</li> <li>6. Y. A. Cengel and A.J. Ghajar, Heat and Mass Transfer – Fundamentals and Applications, Tata McGraw Hill Education Private Limited.</li> <li>7. S.P. Sukhatme, A Textbook on Heat Transfer, Universities Press.</li> </ol>		
<b>Guidelines for Laboratory Conduction</b>		
<b>List of Practical:</b>		
<b>Group A: (Any 2)</b>		
<ol style="list-style-type: none"> <li>1. Determination of pressure using manometers (minimum two)</li> <li>2. Determination of fluid viscosity and its variation with temperature.</li> <li>3. Verification of modified Bernoulli's equation.</li> </ol>		
<b>Group B: (All compulsory)</b>		
<ol style="list-style-type: none"> <li>4. Determination of minor/major losses through metal/non-metal pipes.</li> <li>5. Study of Control valves – Classification, Construction, Working, Application</li> </ol>		
<b>Group C: (Any 2)</b>		
<ol style="list-style-type: none"> <li>6. Demonstration of Pump - Classification, Construction, Working, Application</li> <li>7. Study of Air Compressors – Classification, Construction, Working, Application</li> <li>8. Trial on Positive Displacement Air Compressor.</li> </ol>		
<b>Group D: (All compulsory)</b>		
<ol style="list-style-type: none"> <li>9. Determination of Thermal Conductivity of insulating powder.</li> <li>10. Determination of Thermal Conductivity of metal rod.</li> </ol>		

**202524 – Principles of Robotics**

Teaching Scheme	Credits	Examination Scheme
Theory : 03 Hr./Week Practical : 02 Hr./Week	<b>04</b> Theory : 03 Practical : 01	In-Semester : 30 Marks End-Semester : 70 Marks Oral : 25 Marks

**Prerequisite Courses**

Engineering Mechanisms and their Application, Introduction to Manufacturing, Matrices, Vectors, Electrical Technology, Industrial Electronics

**Course Objectives**

1. To introduce various types of Robots and the functional elements of Robotics
2. To impart knowledge of robot drive systems
3. To introduce various types the end effectors
4. To educate on various sensors used in Robotic automation
5. To introduce the basic mathematical modeling of a robot
6. To impart knowledge of basics of Robot Programming and robotic Applications

**Course Outcomes**

On completion of the course, learner will be able to

CO1: UNDERSTAND basic concepts of robotics

CO2: SELECT appropriate drive for Robotic applications.

CO3: To COMPARE and SELECT robot and end effectors as per application

CO4: To SELECT proper sensors for robot as per application requirement

CO5: To know about the basic mathematical modeling of robot

CO6: To know about the fundamentals of robot programming and applications

**Course Contents**

**Unit I** **Fundamentals of Robotics** **[08 Hr.]**

Historical development of Robotics, Definitions of Industrial Robot, Type and Classification of Robots, Asimov’s laws of robotics, Robot configurations, Robot Components, Robot Degrees of Freedom, Work volume and work envelope, Robot Joints and symbols, Robot Coordinates, Robot Reference Frames, Resolution, accuracy and precision of Robot, Work cell control

**Unit II** **Robot Drive Systems** **[07 Hr.]**

Pneumatic Drives, Hydraulic Drives, Mechanical Drives, Electrical Drives-D.C. Servo Motors, Stepper Motors, A.C. Servo Motors, BLDC-Salient Features, Applications and Comparison of all these Drives, Micro actuators, selection of drive, Power transmission systems for robot, Motion conversion, Determination of HP of motor, Types of Gearbox: - Planetary, Harmonic, Cycloidal gearbox and gear Ratio, variable speed arrangements

**Unit III** **End Effectors** **[08 Hr.]**

Grippers, Mechanical Grippers, Pneumatic and Hydraulic- Grippers, Magnetic Grippers, Vacuum Grippers; Two Fingere and Three Fingere Grippers; Internal Grippers and External Grippers; Advance Grippers- Adaptive grippers, Soft Robotics Grippers, Tactile Sensor Grippers; Various process tools as end effectors; Robot end effectors interface, Active and passive compliance, Selection and Design Considerations

<b>Unit IV</b>	<b>Robot Sensors</b>	<b>[07 Hr.]</b>
Transducers and sensors, Sensors in robotics, Principles and applications of the following types of sensors- Proximity Sensors, Photo Electric Sensors, Position sensors – Piezo Electric Sensor, LVDT, Resolvers, Encoders – Absolute and Incremental: - Optical, Magnetic, Capacitive, pneumatic Position Sensors, Range Sensors- Range Finders, Laser Range Meters, Touch Sensors, Force and torque sensors, Safety Sensor: Light Curtain, Laser Area Scanner, Safety Switches, Machine vision		
<b>Unit V</b>	<b>Mathematical Modeling of a robot</b>	<b>[08 Hr.]</b>
General Mathematical Preliminaries on Vectors & Matrices, Link Equations and relationships, Direct Kinematics, Co-ordinate and vector transformation using matrices, Rotation matrix, Inverse Transformations, Composite Rotation matrix, Homogenous Transformations, Robotic Manipulator Joint Co-ordinate System, inverse kinematics of two joints, DH Parameters, Jacobian Transformation in Robotic Manipulation		
<b>Unit VI</b>	<b>Fundamentals of Robot Programming and Applications</b>	<b>[08 Hr.]</b>
Introduction to Robotic Programming, On-line and off-line programming, programming examples. Various Teaching Methods, Survey of Robot Level Programming Languages, A Robot Program as a Path in Space, Motion Interpolation, various Textual Robot Languages, Typical Programming Examples such as Palletizing, Loading a Machine Etc. Robots in manufacturing and non-manufacturing applications, a robot-based manufacturing system, robot cell design considerations and selection of robot, Robot Economics, Functional Safety in Robotic Application		
<b>Books &amp; Other Resources</b>		
<b>Text Books:</b>		
<ol style="list-style-type: none"> <li>1. Groover, M.P. Weiss, M. Nagel, R.N. &amp; Odrey, N.G., Ashish Dutta, Industrial Robotics, Technology, Programming &amp; Applications, Tata McGraw Hill Education Pvt. Ltd. New Delhi</li> <li>2. S. R. Deb, Robotics Technology and Flexible Automation, Tata McGraw Hill.</li> <li>3. Groover M.P.-Automation, production systems and computer integrated manufacturing-Prentice Hall of India.</li> </ol>		
<b>Reference Books:</b>		
<ol style="list-style-type: none"> <li>1. S B Niku, Introduction to Robotics, Analysis, Control, Applications, 2nd Edition, Wiley Publication, 2015.</li> <li>2. Mikell P. Groover, Automation, Production Systems &amp; Computer Integrated Manufacturing, PHI Learning Pvt. Ltd. , New Delhi, ISBN:987-81-203-3418-2, 2012</li> <li>3. John Craig, Introduction to Robotics, Mechanics and Control, 3rd Edition, Pearson Education, 2009</li> <li>4. R K Mittal &amp; I. J. Nagrath, Robotics and Control, McGraw Hill Publication, 2015.</li> <li>5. Mike Wilson, Implementation of Robotic Systems, ISBN: 978-0-124-04733-4</li> <li>6. <a href="http://www.roboanalyzer.com">www.roboanalyzer.com</a></li> </ol>		
<b>E study material:</b> NPTEL Course on Robotics:		
<a href="https://onlinecourses.nptel.ac.in/noc19_me74/preview">https://onlinecourses.nptel.ac.in/noc19_me74/preview</a> <a href="https://onlinecourses.nptel.ac.in/noc20_de11/preview">https://onlinecourses.nptel.ac.in/noc20_de11/preview</a>		

### **Guidelines for Laboratory Conduction**

The student shall perform any 8 of the following:

Any 07 practical sessions should be completed from following list:

1. Identify and selection of Sensors such as IR sensors, Proximity Sensor, Ultrasonic Sensor, White line sensor, Temperature Sensor, Touch sensor, Tilt Sensor, Accelerometer, Gyroscopic Sensor etc. based on given application
2. Identify and selection of Actuators and related hardware such as DC motor, Servo motor, Stepper Motor, Motor drivers based on application
3. Demonstration of various robotic configurations using industrial robot
4. Design and selection of Gripper / End effector
5. One Programming exercise on lead through programming
6. Use of Matlab/ Robo Analyser for direct and inverse kinematics of simple robot configuration
7. One Industrial visit for Industrial robotic application
8. Demonstration of simple robotic system using Matlab/ MscAdam / RoboAnalyser software
9. Choose the right robot for given manufacturing and non- manufacturing applications

#### **Guidelines for Practical Sessions:**

1. Assessment must be based on understanding of theory, attentiveness during practical, and understanding.
2. There should be continuous assessment and Timely submission of journal.

<b>202050 - Manufacturing Processes</b>		
<b>Teaching Scheme</b>	<b>Credits</b>	<b>Examination Scheme</b>
Theory : 03 Hr./Week	<b>03</b> Theory : 03	In-Semester : 30 Marks End-Semester : 70 Marks
<b>Prerequisite Courses</b> Material Science and Metallurgy, Engineering Physics, Systems in Mechanical Engineering		
<b>Course Objectives</b> <ol style="list-style-type: none"> <li>1. Describe various sand and permanent mold casting methods, procedure and mold design aspects.</li> <li>2. Understand basics of metal forming processes, equipment and tooling.</li> <li>3. Understand sheet metal forming operations and die design procedure.</li> <li>4. Classify, describe and configure the principles of various welding techniques.</li> <li>5. Understand plastic processing techniques.</li> <li>6. To know about composites, its fabrication processes.</li> </ol>		
<b>Course Outcomes</b> On completion of the course, learner will be able to CO1. SELECT appropriate molding, core making and melting practice and estimate pouring time, solidification rate and DESIGN riser size and location for sand casting process CO2. UNDERSTAND mechanism of metal forming techniques and CALCULATE load required for flat rolling CO3. DEMONSTRATE press working operations and APPLY the basic principles to DESIGN dies and tools for forming and shearing operations CO4. CLASSIFY and EXPLAIN different welding processes and EVALUATE welding characteristics CO5. DIFFERENTIATE thermoplastics and thermosetting and EXPLAIN polymer processing techniques CO6. UNDERSTAND the principle of manufacturing of fiber-reinforce composites and metal matrix composites		
<b>Course Contents</b>		
<b>Unit I</b>	<b>Casting Processes</b>	<b>[07 Hr.]</b>
Introduction to casting processes, Patterns: Pattern materials, types of pattern, allowances pattern design, Molding sand, Properties of molding sands, Core making, Melting practices and furnaces, Pouring and Gating system design, Numerical estimation to find mold filling time, Riser design and placement, Principles of cooling and solidification of casting, Directional and Progressive solidification Estimation of solidification rate, Cleaning and Finishing of casting, Defects and remedies, Principle and equipment of Permanent mold casting, Investment casting, Centrifugal casting, Continuous casting		
<b>Unit II</b>	<b>Metal Forming Processes</b>	<b>[08 Hr.]</b>
Plastic deformation. Stress-strain diagram for different types of material, Hot and Cold working, Factors affecting plastic deformation, Yield criteria, Concept of flow stress, Forming Limit diagram <b>Rolling Process:</b> Rolling terminology, Friction in rolling, Calculation of rolling load <b>Forging:</b> Open and closed die forging, Forging operations <b>Extrusion:</b> Types, Process parameter <b>Wire and Tube Drawing:</b> Wire and tube drawing process, Die profile Friction and lubrication in metal forming, Forming defects, causes and remedies for all forming processes		

<b>Unit III</b>	<b>Sheet Metal Forming</b>	<b>[07 Hr.]</b>
Types of sheet metal operations, Press working equipment and terminology, Types of dies, Clearance analysis, Estimation of cutting forces, Centre of pressure and blank size determination, Design of strip lay-out, Blanking die design, Introduction to Drawing, Bending dies, Methods of reducing forces, Formability and forming limit diagrams		
<b>Unit IV</b>	<b>Welding Processes</b>	<b>[08 Hr.]</b>
Classification of joining processes, Welding terminology and types of joints		
<b>Arc Welding Processes:</b> Principles and equipments of Single carbon arc welding, FCAW, TIG, MIG, SAW		
<b>Resistance Welding:</b> Spot, Seam and Projection weld process, Heat balance in resistance welding		
Gas Welding and Cutting, Soldering, brazing and braze welding		
Welding Metallurgy and Heat Affected Zone, Weld inspection, Defects in various joints and their remedies		
<b>Unit V</b>	<b>Processing of polymers</b>	<b>[07 Hr.]</b>
Thermoplastics and Thermosetting, Processing of polymers, Thermoforming, Extrusion		
<b>Molding:</b> Compression molding, Transfer molding, Blow molding, Rotation molding, Injection molding - Process and equipment		
<b>Extrusion of Plastic:</b> Type of extruder, extrusion of film, pipe, Cable and Sheet – Principle		
Pressure forming and Vacuum forming		
<b>Unit VI</b>	<b>Manufacturing of Composites</b>	<b>[08 Hr.]</b>
Introduction to composites, Composite properties, Matrices, Fiber reinforcement		
<b>Composite Manufacturing Processes:</b> Hand lay-up Process, Spray lay-up, Filament winding process, Resin transfer molding, Pultrusion, and Compression molding process, Vacuum impregnation process, Processing of metal matrix composites, Fabrication of ceramic matrix composites, Carbon-carbon composites, Polymer matrix and Nano-composites		
<b>Books &amp; Other Resources</b>		
<b>Text Books</b>		
1. P. N. Rao, “Manufacturing Technology Vol. I & II”, Tata McGraw Hill Publishers		
2. P. C. Sharma, “Production Engineering”, Khanna Publishers		
<b>Reference Books</b>		
1. R. K. Jain, “Production Technology”, Khanna Publishers		
2. K. C. Chawala, “Composite Materials”, Springer, ISBN 978-0387743646, ISBN 978-0387743653		
3. Brent Strong, “Fundamentals of Composites Manufacturing: Materials, Methods”, SME Book series		

<b>202051 - Machine Shop</b>		
<b>Teaching Scheme</b>	<b>Credits</b>	<b>Examination Scheme</b>
Practical : 02 Hr./Week	<b>01</b> Practical : 01	Term Work : 50 Marks
<b>Prerequisite Courses</b> Workshop Practice		
<b>Course Objectives</b>		
<ol style="list-style-type: none"> <li>To understand the basic procedures, types of equipment, tooling used for sand casting and metal forming processes through demonstrations and/(or) Industry visits..</li> <li>To understand TIG/ MIG/ Resistance/Gas welding welding techniques.</li> <li>To acquire skills to handle grinding and milling machine and to produce gear by milling.</li> <li>To acquire skills to produce a composite part by manual process.</li> </ol>		
<b>Course Outcomes</b>		
On completion of the course, learner will be able to		
CO1. PERFORM welding using TIG/ MIG/ Resistance/Gas welding technique		
CO2. MAKE Fibre-reinforced Composites by hand lay-up process or spray lay-up techniques		
CO3. PERFORM cylindrical/surface grinding operation and CALCULATE its machining time		
CO4. DETERMINE number of indexing movements required and acquire skills to PRODUCE a spur gear on a horizontal milling machine		
CO5. PREPARE industry visit report		
CO6. UNDERSTAND procedure of plastic processing		
<b>Guidelines for Laboratory Conduction</b>		
The student shall complete the following activity as a Term Work		
<b>Practical</b> ( <i>Select any One Practical from Practical # 1 &amp; 2; Select any Five Practical from Practical # 3 to 8; Perform Total Six Practical</i> )		
<ol style="list-style-type: none"> <li>To study and observe various stages of casting through demonstration of sand casting process from pattern making, sand mold preparation and melting and pouring of metal.</li> <li>Visit to any foundry/ permanent mold casting industry to demonstrate various stages of casting and make a report on it.</li> <li>A compulsory visit to any one metal forming industry out of: Rolling mill, Forging plant, Wire/Tube drawing unit and prepare a report on it.</li> <li>A demonstration of any one welding technique out of TIG/ MIG/Resistance/Gas welding. A job drawing to be prepared by an individual institute with details of welding process parameters with weld joint design such as edge preparation, type and size of electrode used, welding current, voltage etc.</li> <li>Manufacturing of Fiber-reinforced Composites by hand lay-up process or spray lay-up techniques.</li> <li>Demonstration on any one plastic component like bottle, bottle caps, machine handles etc. by injection molding process/ by additive manufacturing process.</li> <li>Demonstration on cylindrical grinding/surface grinding operations, measurement of surface roughness produced and estimation of machining time.</li> <li>Demonstration on indexing mechanism. Calculation of index crank and index plate movement by simple/compound/differential indexing and manufacture of spur gear on a milling machine using indexing head.</li> </ol>		
<b>Instructions for Laboratory Conduction</b>		
Please note following instructions regarding Laboratory Conduction:		
<ol style="list-style-type: none"> <li>Industrial Visits to be conducted by the Teaching <b>Faculty</b> (subject Teacher).</li> <li>Demonstration of Welding machines, Surface/Cylindrical Grinding, Milling machine, Indexing head and calculation of indexing to be taught by a <b>subject Teacher in Practical slot</b>.</li> </ol>		



## 202052 - Project Based Learning - II

Teaching Scheme	Credits	Examination Scheme
Practical : 04 Hr./Week	<b>02</b> Practical : 02	Term Work : 50 Marks

### Preamble

Currently, engineering education is undergoing significant structural changes worldwide. The rapidly evolving technological landscape forces educators to constantly reassess the content of engineering curricula in the context of emerging fields and with a multidisciplinary focus. In this process, it is necessary to devise, implement and evaluate innovative pedagogical approaches for the incorporation of these novel subjects into the educational programs without compromising the cultivation of the traditional skills. In this context, the educational community is showing rapidly rising interest in project-based learning approaches.

The mainstream engineering education follows traditional classroom teaching, in which the major focus is mainly on the lecture and the student has very little (if any) choice on the learning process. However rapid development in engineering and technology requires adopting a teaching approach that would assist students not only in developing a core set of industry relevant skills, but also enable them to adapt to changes in their professional career.

### Course Objectives

1. To emphasize project based learning activities that are long-term, interdisciplinary and student-centric.
2. To inculcate independent and group learning by solving real world problems with the help of available resources.
3. To be able to develop applications based on the fundamentals of mechanical engineering by possibly applying previously acquired knowledge.
4. To get practical experience in all steps in the life cycle of the development of mechanical systems: specification, design, implementation, and testing.
5. To be able to select and utilize appropriate concepts of mechanical engineering to design and analyze selected mechanical system.

### Course Outcomes

On completion of the course, learner will be able to

- CO1. IDENTIFY the real-world problem (possibly of interdisciplinary nature) through a rigorous literature survey and formulate / set relevant aims and objectives.
- CO2. ANALYZE the results and arrive at valid conclusions.
- CO3. PROPOSE a suitable solution based on the fundamentals of mechanical engineering by possibly integration of previously acquired knowledge.
- CO4. CONTRIBUTE to society through proposed solutions by strictly following professional ethics and safety measures.
- CO5. USE of technology in proposed work and demonstrate learning in oral and written form.
- CO6. DEVELOP ability to work as an individual and as a team member.

### Group Structure

Working in supervisor/mentor –monitored groups. The students plan, manage and complete a task/project/activity which addresses the stated problem.

1. Create groups of 5 (five) to 6 (six) students in each class
2. A supervisor/mentor teacher is assigned to 3-4 groups or one batch

### Project Selection

The project can be selected by undertaking a survey of journal papers, patents or field visit (A problem can be theoretical, practical, social, technical, symbolic, cultural and/or scientific). The problem shall consist of following facets: feasibility of arriving at a solution, analyzing the problem, design and development of the system (hardware or virtual).

There are no commonly shared criteria/ guidelines for what constitutes an acceptable project. Projects vary greatly in the depth of the questions explored, the clarity of the learning goals, the content and structure of the activity undertaken.

Solution to problem-based projects through “*learning by doing*” is recommended. The model begins with the identifying of a problem, often growing out of a question or “wondering”. This formulated problem then stands as the starting point for learning. A problem can be theoretical, practical, social, technical, symbolic, cultural and/or scientific and grows out of students’ wandering within different disciplines and professional environments. As stated in the preamble as the world has adapted and propagated multidisciplinary approach, hence the proposed project activity preferably should not be restricted to only mechanical domain specific projects rather should be Interdisciplinary in nature. However the chosen problem should be integration of other streams of engineering with Mechanical engineering.

Although in a genuine case 100% software/ virtual project topic may be allowed.

### **Ethical Practices, teamwork and project management:**

Use Indian standards or any relevant standards for project manufacturing, respect the time of others, attend the reviews, poster presentation and model exhibitions, strictly follow the deadline of project completion, comply with all legislation requirements that govern workplace health and safety practices.

### **Effective Documentation**

In order to make our engineering graduates capable of preparing effective documentation, it is required for the students to learn the effective writing skills. The PBL final report is expected to consist of the Literature Survey, Problem Statement, Aim and Objectives, System Block Diagram, System Implementation Details, Discussion and Analysis of Results, Conclusion, System Limitations and Future Scope. Many freely available software tools (for instance Mendley (Elsevier), Grammarly) are expected to be used during the preparation of PBL synopsis and final report. It is expected that the PBL guides/mentors shall teach students about utilizing valid sources of information (such as reference papers, books, magazines, etc) related to their PBL topic.

### **Evaluation & Continuous Assessment**

The institution/head shall be committed to ensuring the effective and rigorous implementation of the idea of project based learning. Progress of PBL shall be monitored regularly on a weekly basis. Weekly review of the work shall be necessary. During the process of monitoring and continuous assessment and evaluation the individual and team performance is to be measured. PBL is monitored and continuous assessment is done by supervisor /mentor and authorities. Students must maintain an institutional culture of authentic collaboration, self-motivation, peer-learning and personal responsibility. The institution/department should support students in this regard through guidance/orientation programs and the provision of appropriate resources and services. Supervisor/mentor and Students must actively participate in assessment and evaluation processes.

The effectiveness of the concept PBL lies in rigorous and continuous assessment and evaluation of the student performance. It is recommended that all activities are required to be recorded regularly. A regular assessment of PBL work is required to be maintained at the department in PBL log book by students. It is expected that the PBL log book must include following:

1. Information of students and guide
2. Weekly monitoring by the PBL guide,
3. Assessment sheet for PBL work review by PBL guide and PBL Evaluation Committee (PEC).

The PEC structure shall consist of Head of the department, 1/2 senior faculties of the department and one industry expert (optional). Continuous Assessment Sheet (CAS) is to be maintained by the department.

**Recommended parameters for assessment, evaluation and weightage**

1. Idea Inception (kind of survey). (10%)
2. Documentation (Gathering requirements, design & modeling, implementation/execution, use of technology and final report, other documents). (15%)
3. Attended reviews, poster presentation and model exhibition. (10%)
4. Demonstration (Poster Presentation, Model Exhibition etc). (10%).
5. Awareness /Consideration of - Environment/ Social /Ethics/ Safety measures/Legal aspects. (5%)
6. Outcome (physical model/prototype/ virtual model/ product development/ assembly & disassembly and analysis of standard mechanism or system, design and development of small applications using Arduino, design of control systems, development of various systems/ subsystems of BAJA/SUPRA/Robots/GoKart/ Sunrisers/Hackathon/ application development and similar activities/ System performance and analysis) (40%)
7. Participation in various competitions/ publication/ copyright/ patent) (10%)

**Learning Resources****Reference Books / Research Articles**

1. John Larmer, John R. Mergendoller, and Suzie Boss, “Setting the Standard for Project Based Learning”
2. John Larmer and Suzie Boss, “Project Based Teaching: How to Create Rigorous and Engaging Learning Experiences”
3. Erin M. Murphy and Ross Cooper, “Hacking Project Based Learning: 10 Easy Steps to PBL and Inquiry”

**Web resources**

1. <https://www.edutopia.org/project-based-learning>
2. [www.howstuffworks.com](http://www.howstuffworks.com)
3. <https://www.pblworks.org/>
4. [www.wikipedia.org](http://www.wikipedia.org)

## 202053 - Audit Course - IV

Teaching Scheme		Credits	Examination Scheme	
	-	-		-

### GUIDELINES FOR CONDUCTION OF AUDIT COURSE

**Faculty mentor shall be allotted for individual courses and he/she shall monitor the progress for successful accomplishment of the course. Such monitoring is necessary for ensuring that the concept of self-learning is being pursued by the students 'in true letter and spirit'.**

- If any course through Swayam/ NPTEL/ virtual platform is selected the minimum duration shall be of 8 weeks.
- However if any of the course duration is less than the desired (8 weeks) the mentor shall ensure that other activities in form of assignments, quizzes, group discussion etc. (allied with the course) for the balance duration should be undertaken.

In addition to credits courses, it is mandatory that there should be an audit course (non-credit course) from second year of Engineering. The student will be awarded grade as AP on successful completion of the audit course. The student may opt for any one of the audit courses in each semester. Such audit courses can help the student to get awareness of different issues which make an impact on human lives and enhance their skill sets to improve their employability. List of audit courses offered in the semester is provided in the curriculum. Students can choose one of the audit courses from the list of courses mentioned. Evaluation of the audit course will be done at institute level.

The student registered for audit course shall be awarded the grade AP and shall be included such grade in the Semester grade report for that course, provided student has the minimum attendance as prescribed by the Savitribai Phule Pune University and satisfactory in-semester performance and secured a passing grade in that audit course. No grade points are associated with this 'AP' grade and performance in these courses is not considered in the calculation of the performance indices SGPA and CGPA. Evaluation of the audit course will be done at institute level itself.

### Selecting an Audit Course

#### List of Courses to be opted (Any one) under Audit Course IV

- Language & Mind Emotional Intelligence
- Advanced Foreign Language (preferably German/ Japanese)
- Human Behavior
- Speaking Effectively
- Business Ethics
- Technical writing/ Research writing

# The titles indicated above are subject to change in time to come and such an alteration (if any) should be brought to the notice of the BoS.

### Using NPTEL Platform: (preferable)

NPTEL is an initiative by MHRD to enhance learning effectiveness in the field of technical education by developing curriculum based video courses and web based e-courses. The details of NPTEL courses are available on its official website [www.nptel.ac.in](http://www.nptel.ac.in)

- Students can select any one of the courses mentioned above and has to register for the corresponding online course available on the NPTEL platform as an Audit course.
- Once the course is completed the student can appear for the examination as per the guidelines on the NPTEL portal.
- After clearing the examination successfully; student will be awarded with a certificate.

**Assessment of an Audit Course**

- The assessment of the course will be done at the institute level. The institute has to maintain the record of the various audit courses opted by the students. The audit course opted by the students could be interdisciplinary.
- During the course students will be submitting the online assignments. A copy of the same can be submitted as a part of term work for the corresponding Audit course.
- On the satisfactory submission of assignments, the institute can mark as “Present” and the student will be awarded the grade AP on the mark sheet.